



Alfred Gessow Rotorcraft Center  
Department of Aerospace Engineering  
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College Park, MD 20742

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To the American Helicopter Society:

The members of the University of Maryland Graduate Student Design Team hereby grant AHS full permission to distribute the enclosed Executive Summary and Final Proposal for the 35<sup>th</sup> Annual Student Design Competition as they see fit.

Thank you,

The UMD Design Team

# METALTAIL



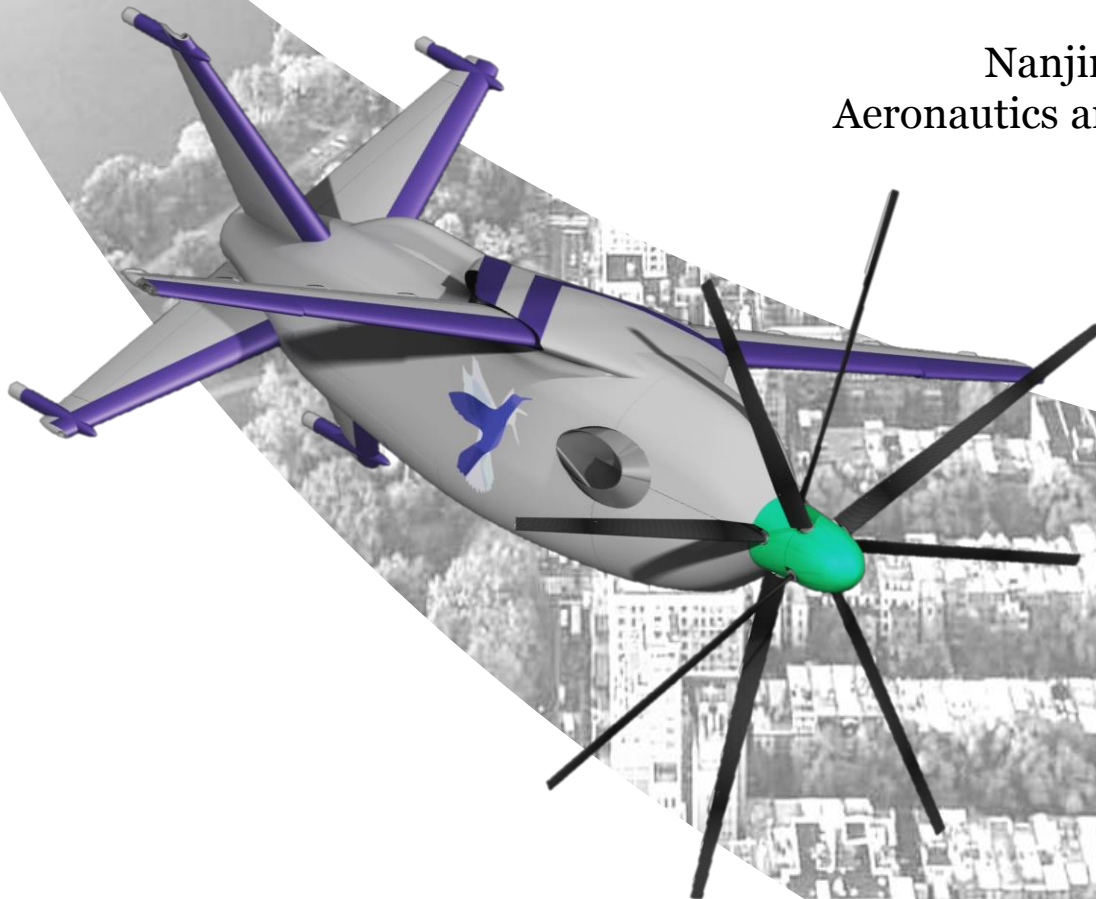
35<sup>th</sup> Annual AHS Student Design Competition

## **A Reconfigurable VTOL Aircraft**

*Sponsored by United States Army Research Laboratory*

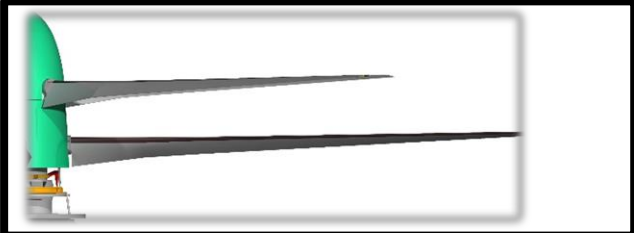
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Nanjing University of  
Aeronautics and Astronautics  
Nanjing, China



UNIVERSITY OF  
MARYLAND

# Metaltail: Reconfigured for the Future

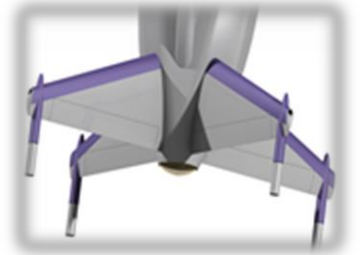
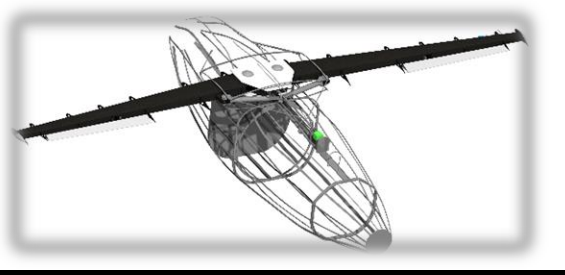


## Tailored Proprotor Design

Common point design between rotors and propellers provides efficient performance for both hover and forward flight.

## Swing Wing Mechanism

Novel execution of sweeping wings reconfigures past problems into present-day solutions.



## Tailsitter Configuration

An X-tail titanium frame ensures structural integrity for bearing landing loads.



## Innovative Hingeless Hub

Unique swashplate mounting method results in compact hub with shorter control rods.

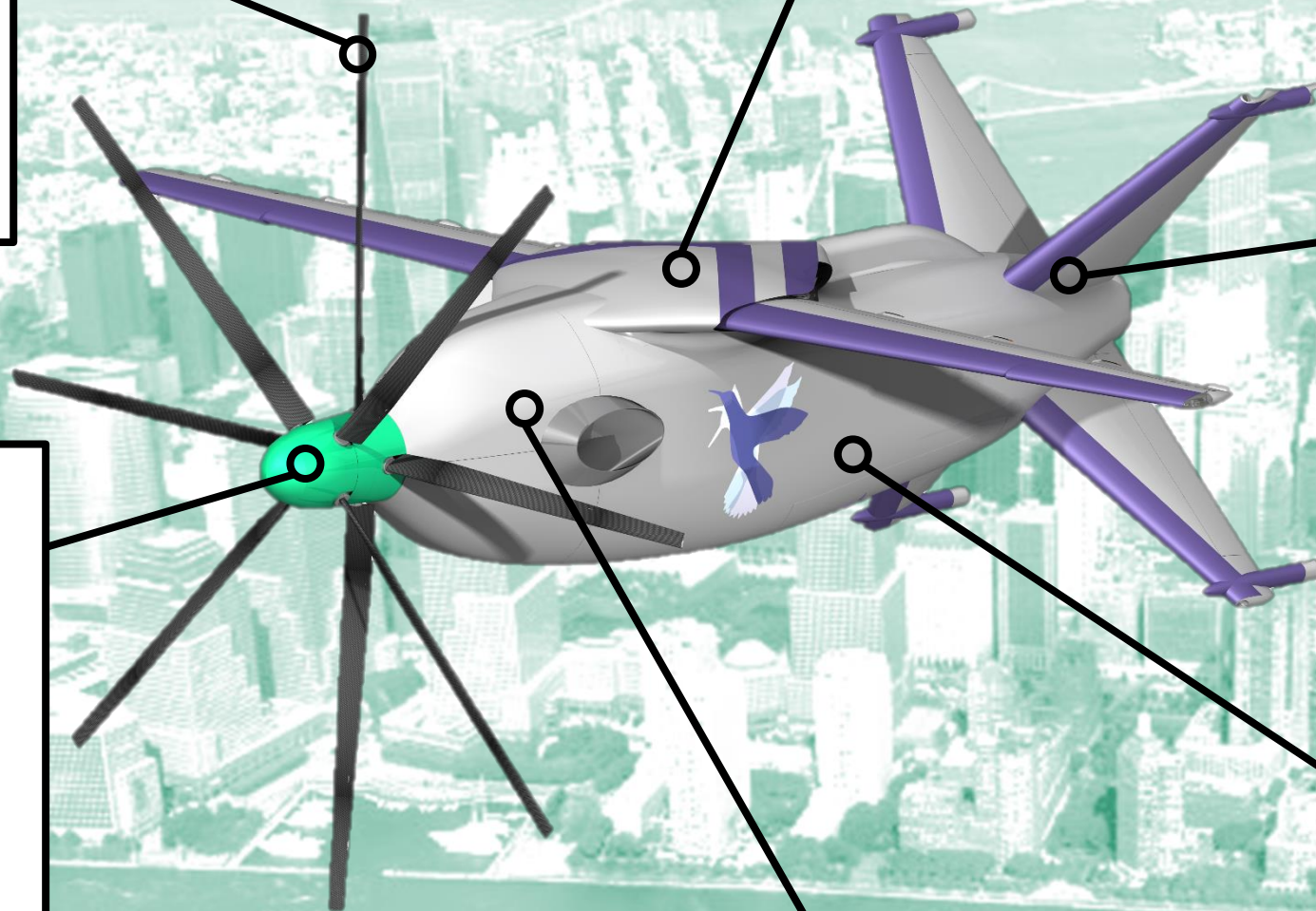


## State-of-the-Art Engines

Two advanced turboshaft diesel engines deliver unprecedented power for exceptional performance.

## Modular Payload Bay

Large compartment and modular rack offers flexibility for assortment of payload packages.



# *Metaltail: Pushing the envelope*



High in the montane forests of Ecuador, a steady hum of activity can be heard as Tyrian Metaltail hummingbirds skirt around the flora, pollinating the habitat. Using their high visual acuity, these small creatures can recognize a wide variety of colors and detect the slightest of motions. Coupled with their agile wing movements, they are able to precisely hover in place while in complex and dynamic environments.



Inspired by these small but impressive flyers, *Metaltail* is a **fully autonomous, high-speed, reconfigurable** aircraft designed by the University of Maryland in response to the 35<sup>th</sup> Annual AHS Student Design Competition Request for Proposal (RFP) sponsored by the United States Army Research Laboratory (ARL).

Developed as a Group 3 Unmanned Aerial Vehicle (UAV), *Metaltail* is an autonomous **coaxial-proprotor**

**swing-wing tailsitter** that, like the high-altitude hummingbirds of Ecuador, leverages visual sensory information and adjustable wing geometry to **maneuver in megacity environments**.

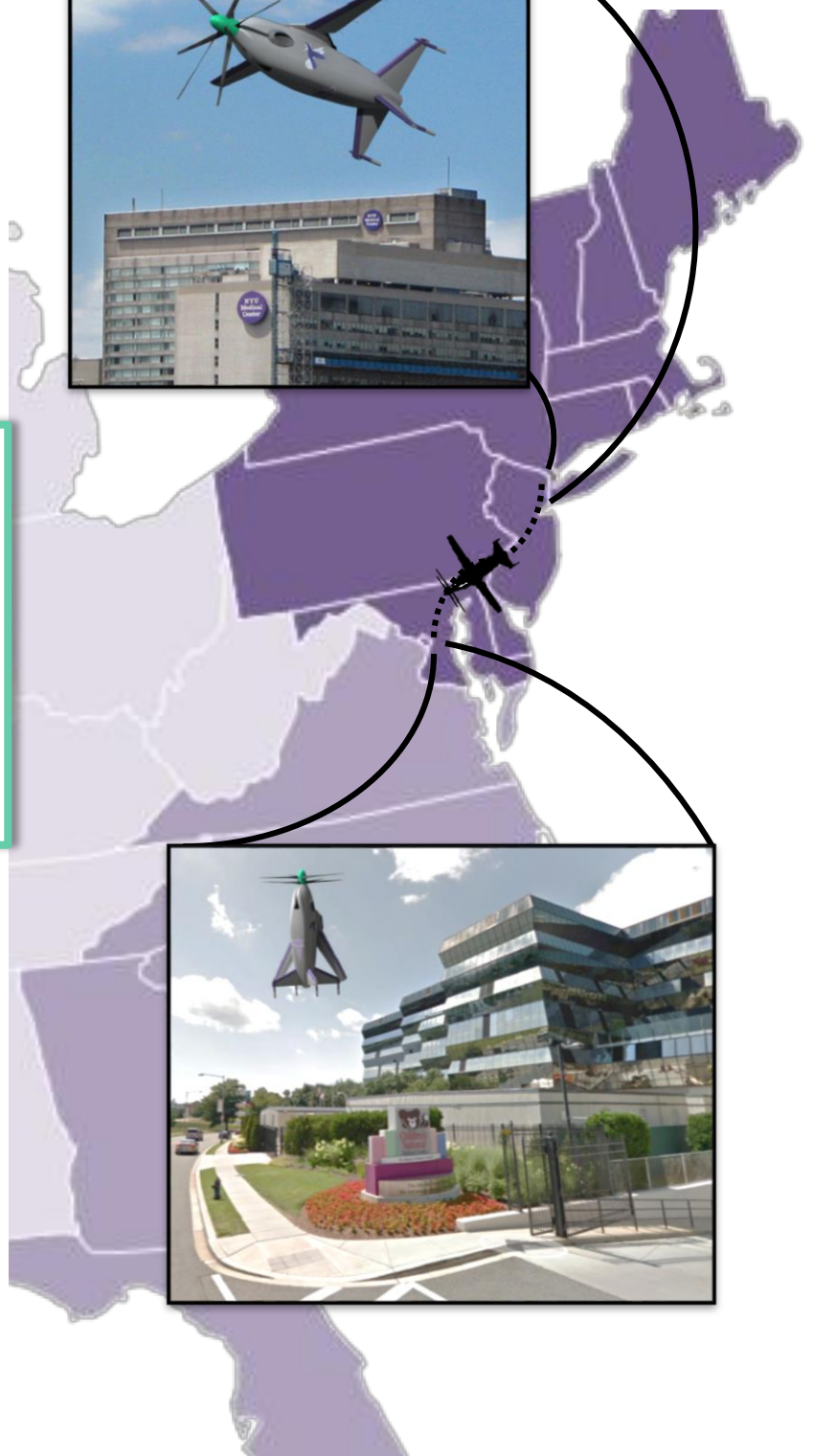
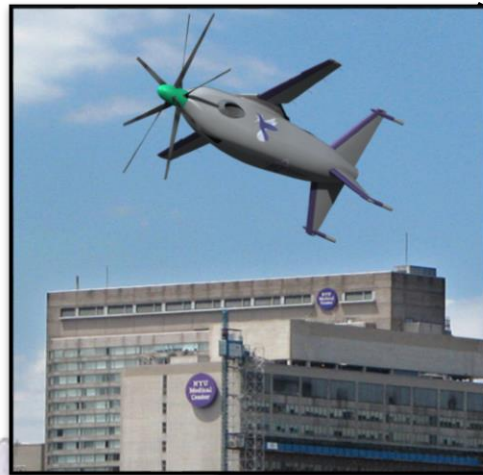
With **powerful, lightweight, state-of-the-art turboshaft engines**, and **sleek aerodynamic design** pushing the forward flight envelope at this scale, *Metaltail* endeavors to change the world by delivering critical emergency supplies while circumventing the barriers typically faced by current operating vehicles.

# Mission: Mending Hearts



Eight-year-old Charlie was born with a critical congenital heart defect (CHD). Years of treatments at Children's National Medical Center in Washington D.C. had been ineffective, so she was added to the national waiting list for organ transplants.

A year later, Charlie's family is notified that a viable heart is available and will be transported from NYU Medical Center, a straight distance of 330 km. A heart is only viable for 4-6 hours so the method of transportation is not a small consideration.



## Typical Transportation:

EMS automobile: 4+ hours

EMS helicopter: 65 minutes

EMS Fixed-wing: 40+ minutes,  
dependent on transfer

Metaltail: 42 minutes exactly

With a speed of 471 km/h at max continuous power, it can cover 330 km point-to-point in a blistering 42 minutes. Metaltail outshines the competition by being faster, cheaper, and quicker than all other options, ensuring that time-critical needs are met with time to spare.



# Enabling Rapid Response



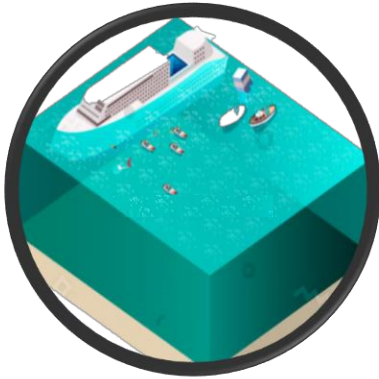
In the United States, 8,000 individual deaths occur every year because organs are not donated in time. Emergency Medical Services (EMS) typically use rotorcraft for transport up to a range of 320 km. Maryland State Police EMS rotorcraft, such as the AgustaWestland AW-139, cruise at 300 km/h, covering 320 km in 64 minutes.

*Metaltail* can traverse the same distance in 40 minutes, traveling at 482 km/h at maximum continuous power, a **40% reduction** in time.



At velocity for best range, *Metaltail* has an operational range of 1300 km on full fuel, carrying 100 kg of payload, and a range of 1700 km on a full fuel tank with an additional 60 kg auxiliary fuel tank installed and no payload.

# Multi-Mission Capability



## ***Package Delivery***

- Efficient cruise and hover performance
- Additional fuel tank and gimbal with powerful sensor suite augment vehicle capacity
- Offshore coordination of multiple vehicles allows for more coverage in less time

## ***Maritime Search and Rescue***

- Efficient cruise and hover performance
- Additional fuel tank and gimbal with powerful sensor suite augment vehicle capacity
- Offshore coordination of multiple vehicles allows for more coverage in less time



## ***Communications Relay***

- Efficient cruise and hover performance
- Additional fuel tank and gimbal with powerful sensor suite augment vehicle capacity
- Offshore coordination of multiple vehicles allows for more coverage in less time

## ***Megacity Firefighting***

- Circumvents congested terrestrial traffic, provides access to tall structures
- Thermal sensor suite for identifying personnel and critical fire targets
- Launch equipment for distributing fire suppression generator capsules





# Vehicle Configuration



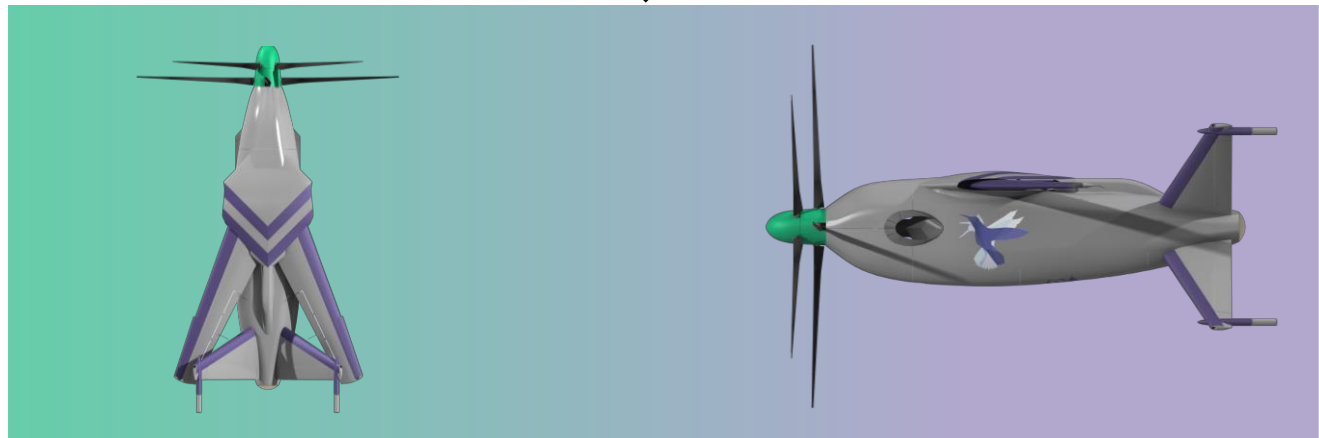
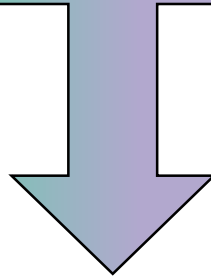
A **Group 3** aircraft operating in **megacity operations**, confined to **3 by 3 meter square**, capable of achieving **high-speed flight**.

## VTOL

## Fixed wing



Lessons learned



*Metaltail* - **Advanced Swing Wing Coaxial Tailsitter**

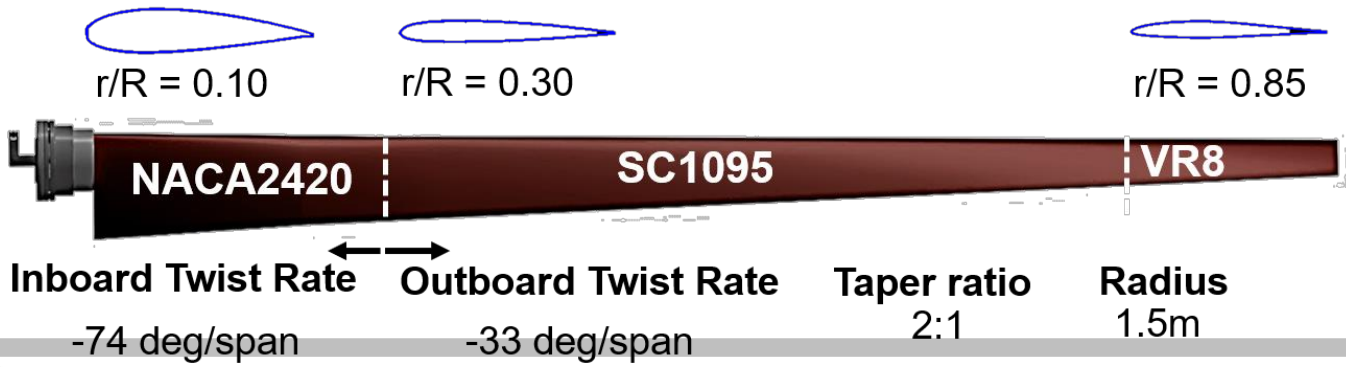
Rotor and fixed wing technology at its best. **Compact. Safe. Efficient.**

**Downwash velocity** is lower than other rotor configurations confined to the same 3 x 3 meter square area, reducing the wind speed affecting ground personnel

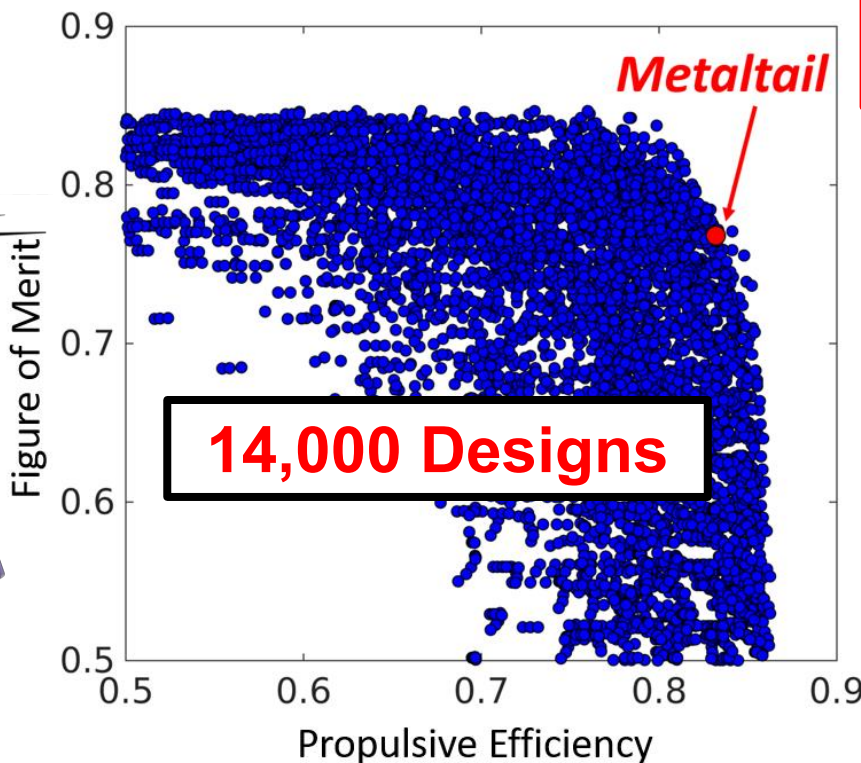
**The disk loading** is much lower, translating into an efficient hovering vehicle.

**Download penalty** of the fuselage in conventional helicopters is greatly mitigated with the slender frame now oriented in the same direction as the flow.

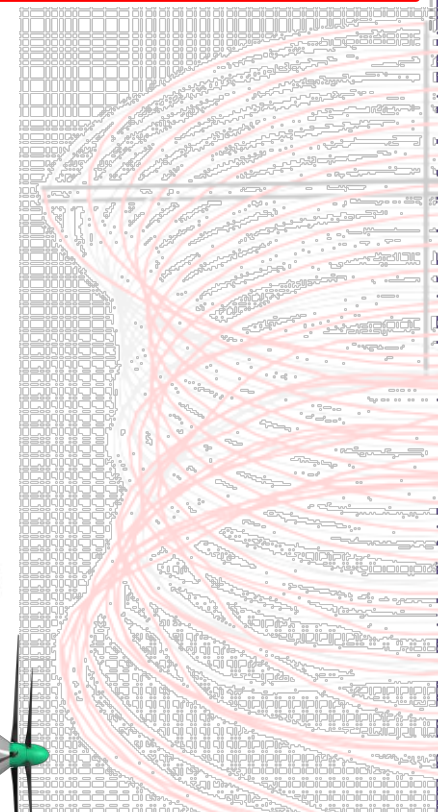
# Proprotor Aerodynamic Design



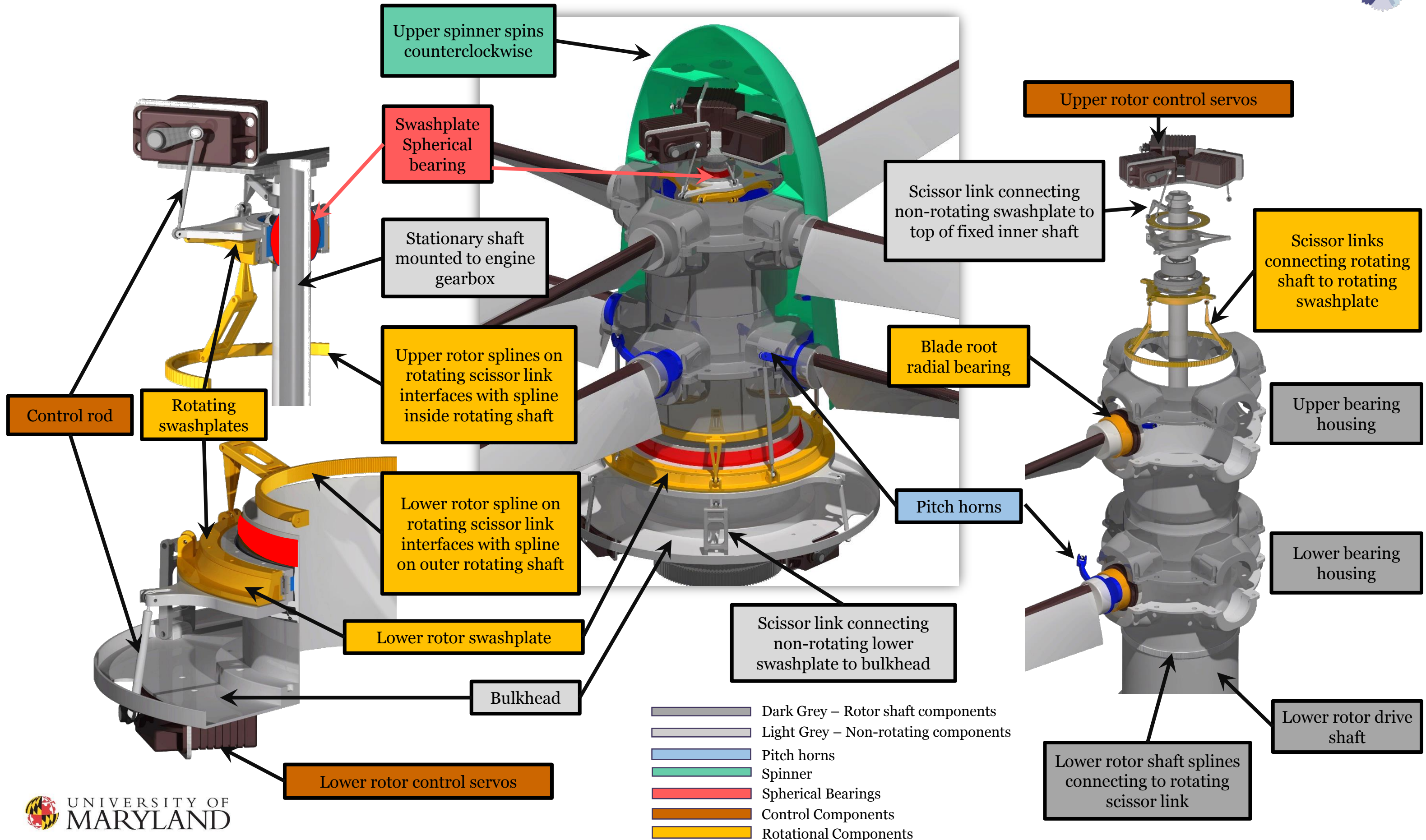
- **14,000 designs** were considered in hover and cruise.
- **2D CFD** was performed to obtain airfoil tables for **15 airfoils**
- Combination of **78 twist rates** were investigated
- Geometric parameters of the rotor were varied to obtain **exceptional high-speed** and **hovering efficiency**.
- Designs analyzed using **advanced BEMT** and **FVM** methods



**$FM = 0.768$**   
 **$\eta_p = 0.832$**



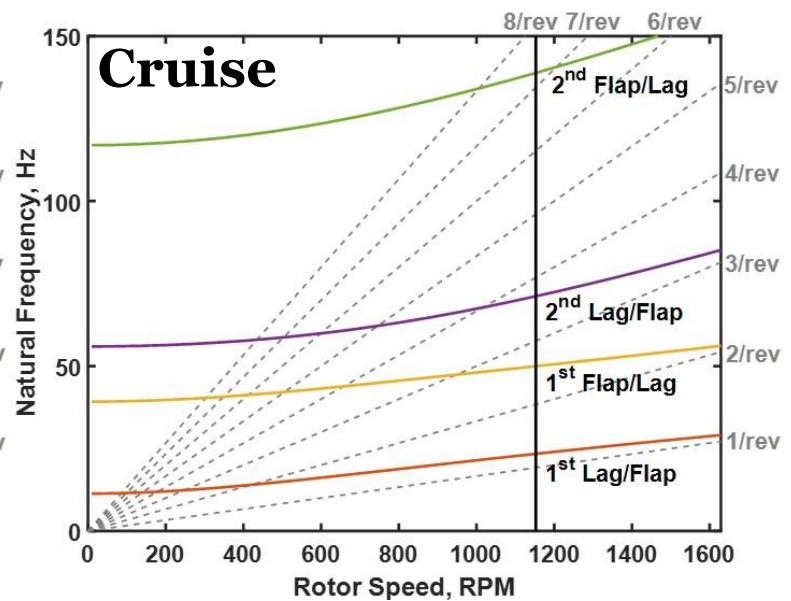
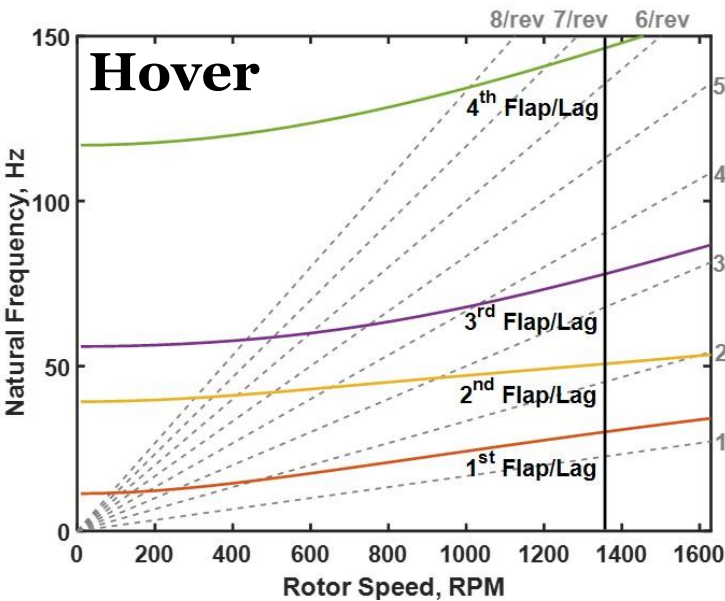
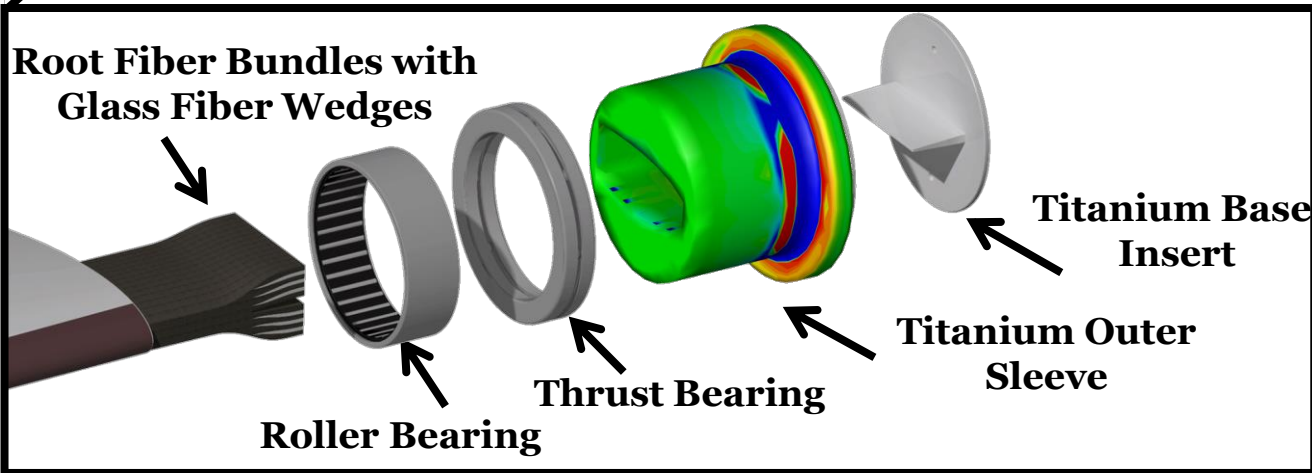
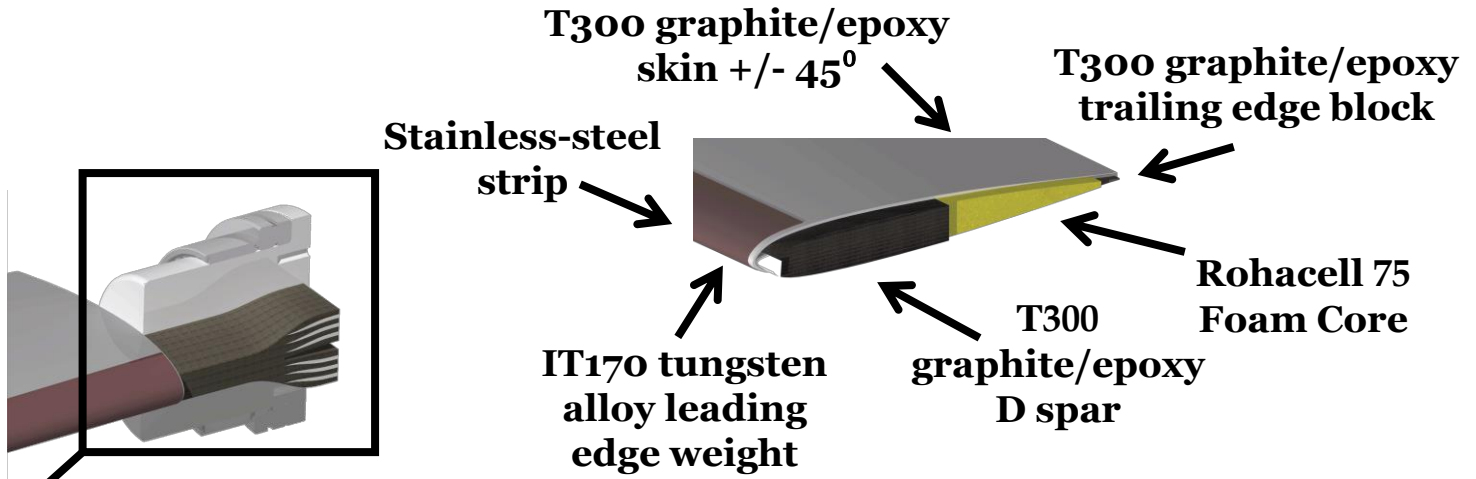
# Hub Design: Hidden Internal Swashplate Mechanism (HISM)



# Blade Structural Design



- **Stiff rotor blades** eliminate the risk of blade strike
- **Novel, compact** root wedge design implemented for *Metaltail* blades

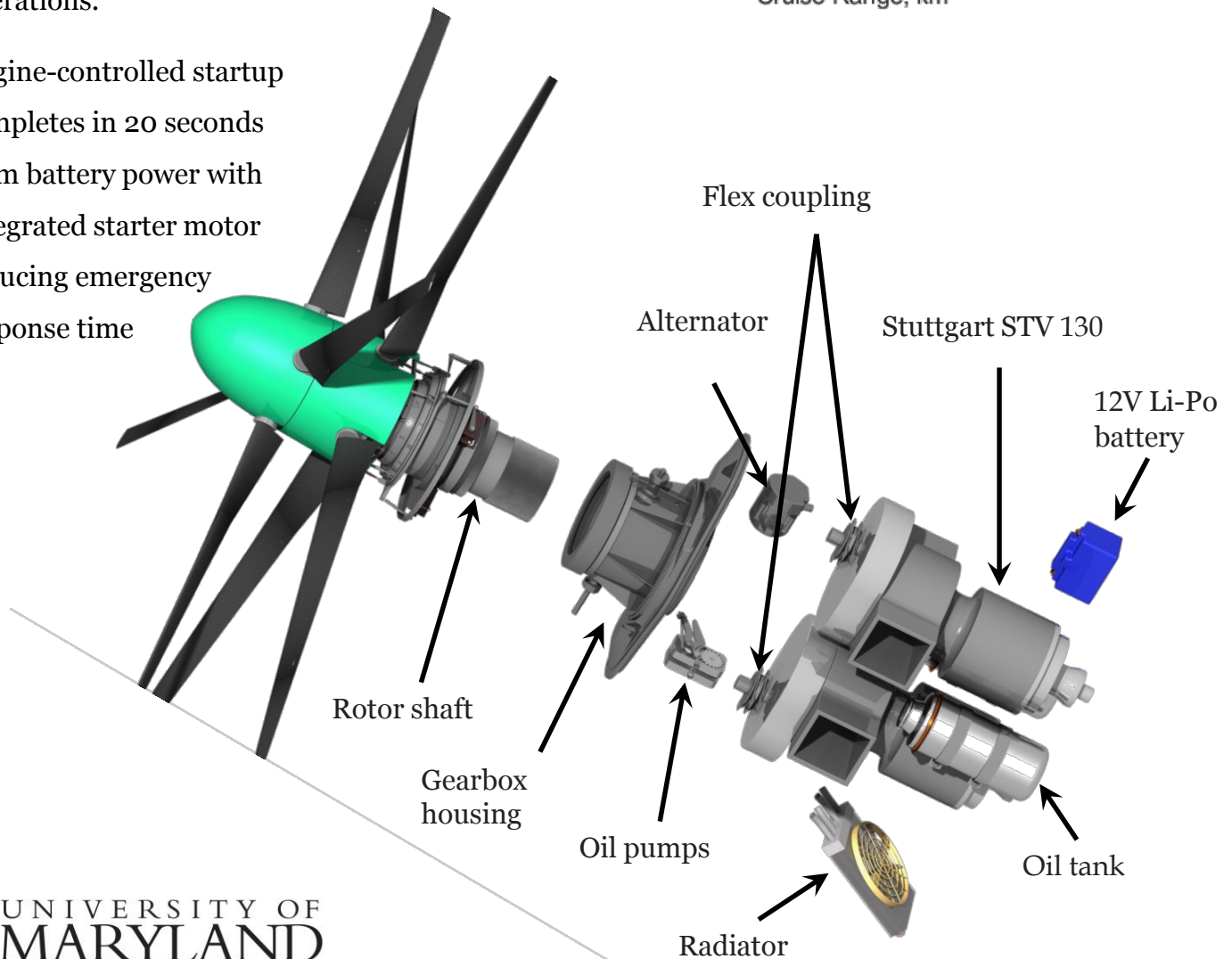
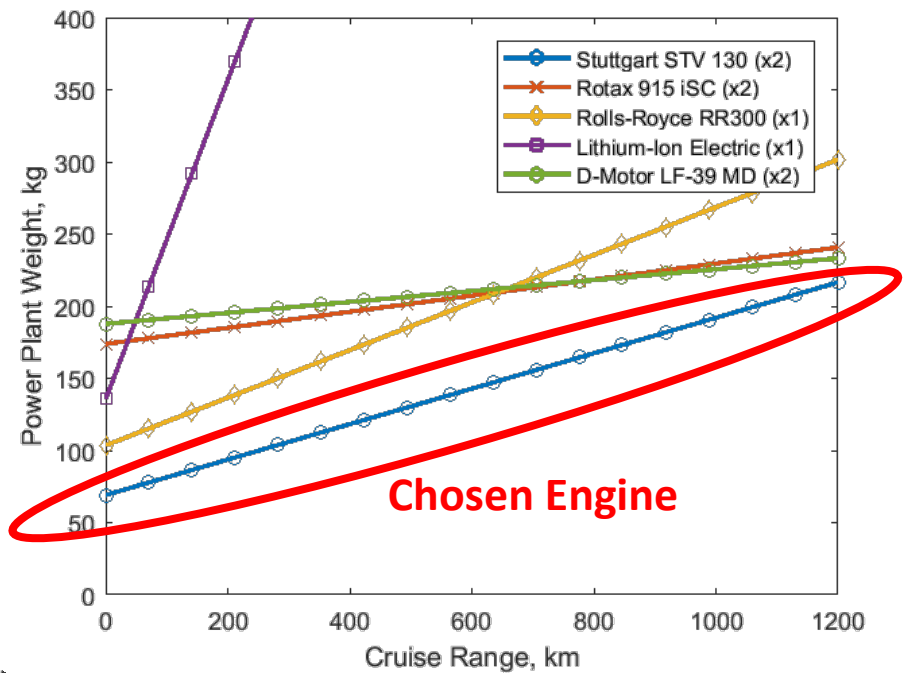


# Powerplant



Two Stuttgart STV 130 turboshaft engines power the coaxial rotor.

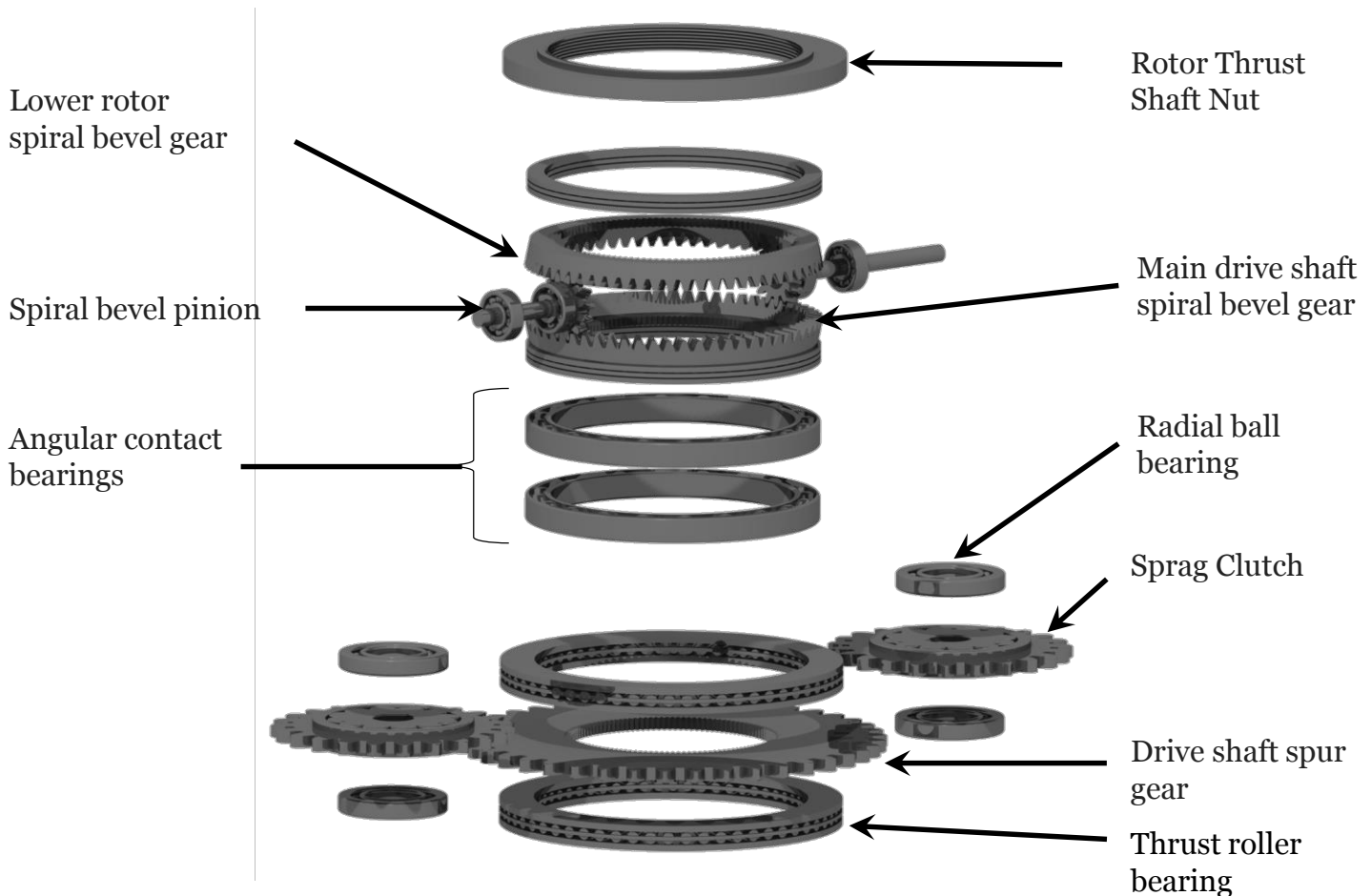
- STV 130 has the lowest specific fuel consumption (SFC) at predicted cruise and hover power settings.
- Free turbine recuperated turboshaft engine with a single-stage compressor and single-stage power turbine.
- Free turbine-powered drive shaft allows the rotor to stop with the engines at idle for safe ground operations.
- Engine-controlled startup completes in 20 seconds from battery power with integrated starter motor reducing emergency response time



# Transmission Design



Dual-input spur gear reduction module with a split-bevel coaxial drive module to allow the motor and rotor to operate at the most efficient rotational speeds with a 1.826:1 reduction ratio.



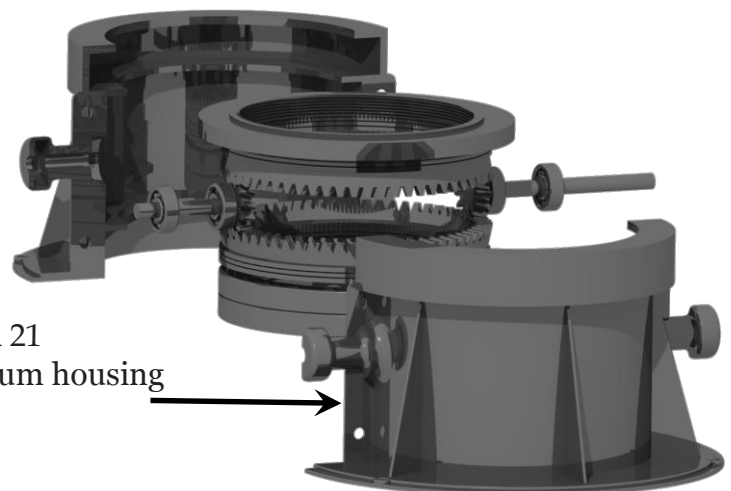
## Dual-Input, Spur-Gear Reduction Module

Input over-running clutch to allow OEI operations for increased safety and reliability.



## Split-Bevel, Coaxial Drive Module

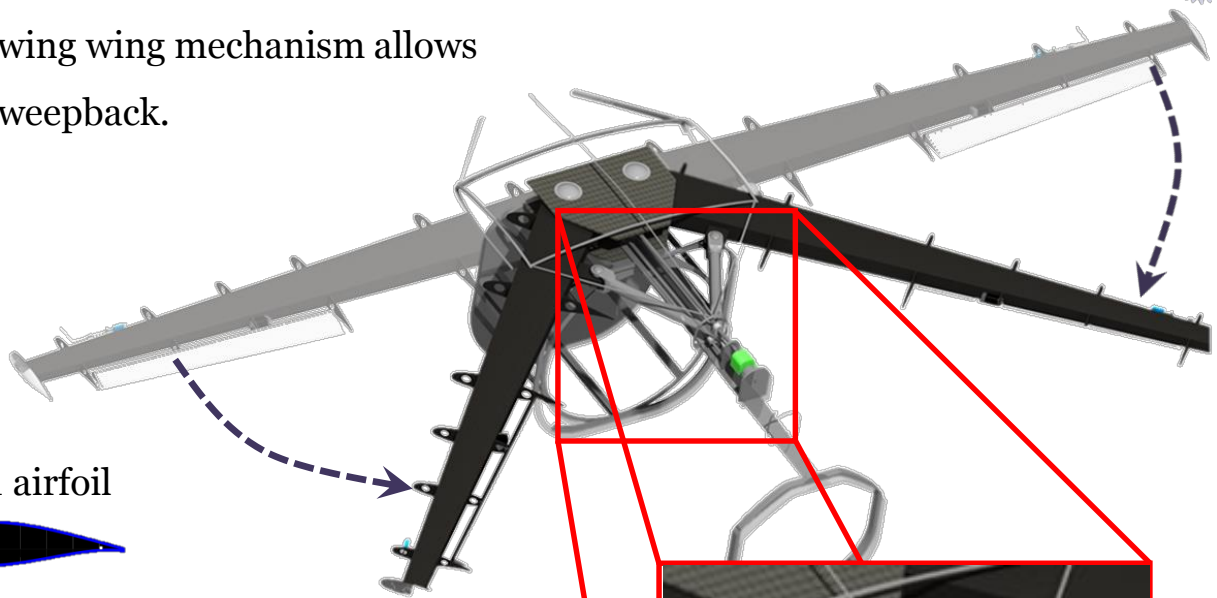
Spiral bevel gears for reduced transmission noise and increased reliability and safety. Simplistic coaxial configuration for increased reliability.



# Swing Wing Design



Design of swing wing mechanism allows for 66° of sweepback.

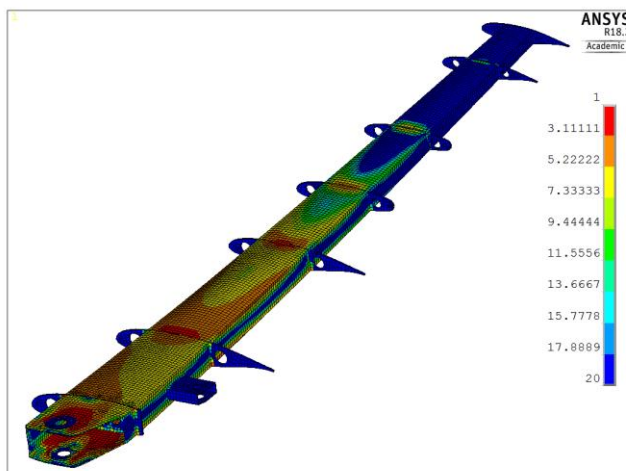


GA(W)-1 airfoil



Parameters	Value
Span (meters)	4.75
Max thickness/chord	0.17
Taper ratio	0.5
Aspect ratio	12
Wing Loading (kg/m <sup>2</sup> )	292.9

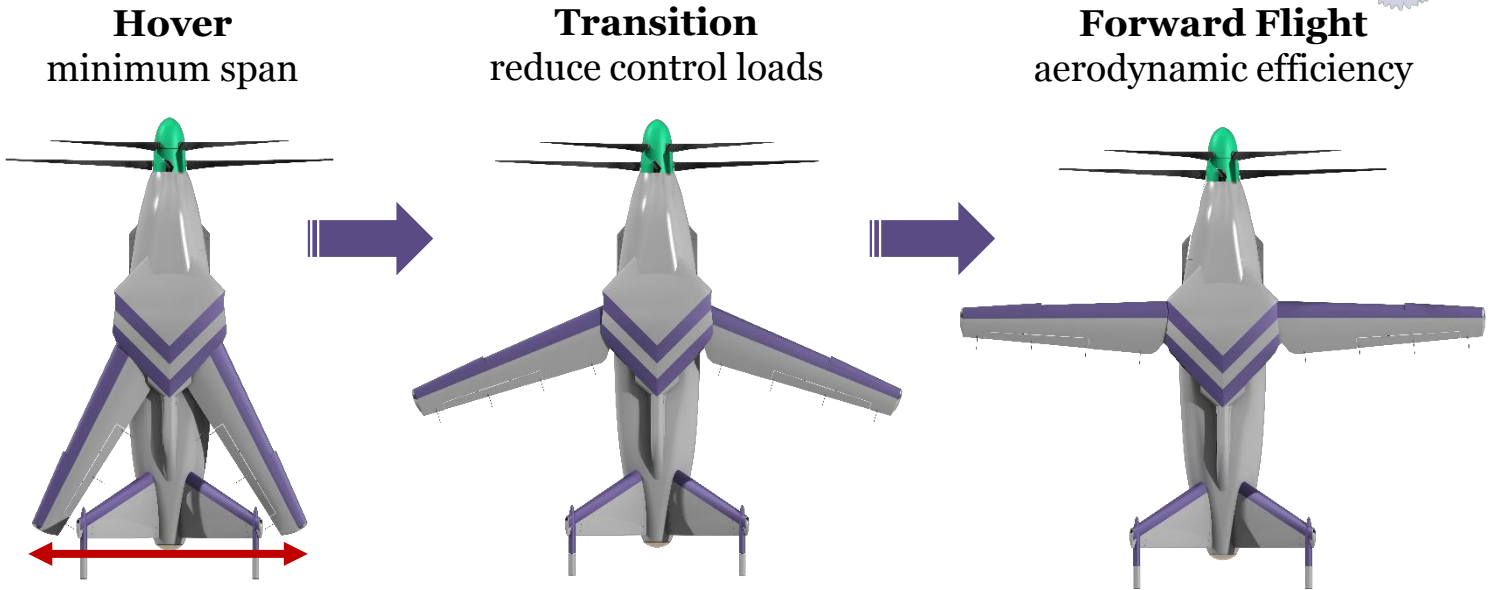
Dynamic load analysis shows wing spar has factor of safety of 1.5 when under a 3.5g load



The swing wing mechanism is a motorized lead screw capable of fully sweeping the wing in under 8.5 seconds.

- Self-locking lead screw
- Rotation Speed: >8 degrees/second
- Buckling load factor of safety: 5
- Transition during maneuvers
- Mechanism Weight: <5 kg
- Screw Diameter: 16mm

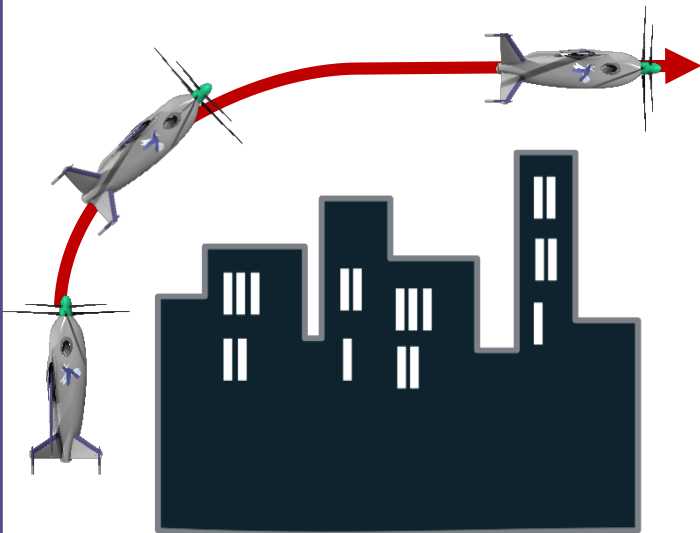
# Transition



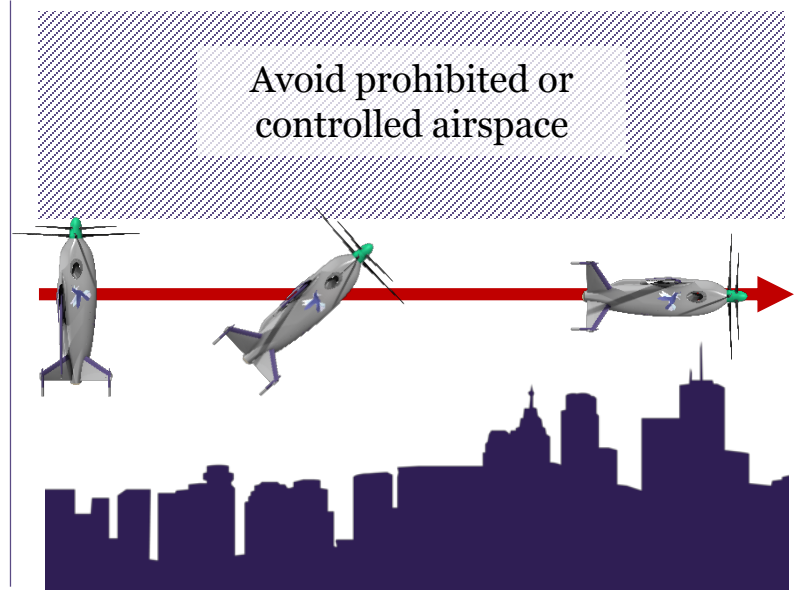
*Metaltail's* unique wing sweep mechanism enables high performance in both VTOL and forward flight modes:

- Transition using only aerodynamic controls—**reduces rotor power**
- Use movement of center of pressure to trim vehicle dynamically
- **Compact** in hover, without compromising **cruise efficiency**
- Only **42 sec** to transition and accelerate from hover to cruise speed

Wing sweep allows **multiple maneuvers** possible based on mission:

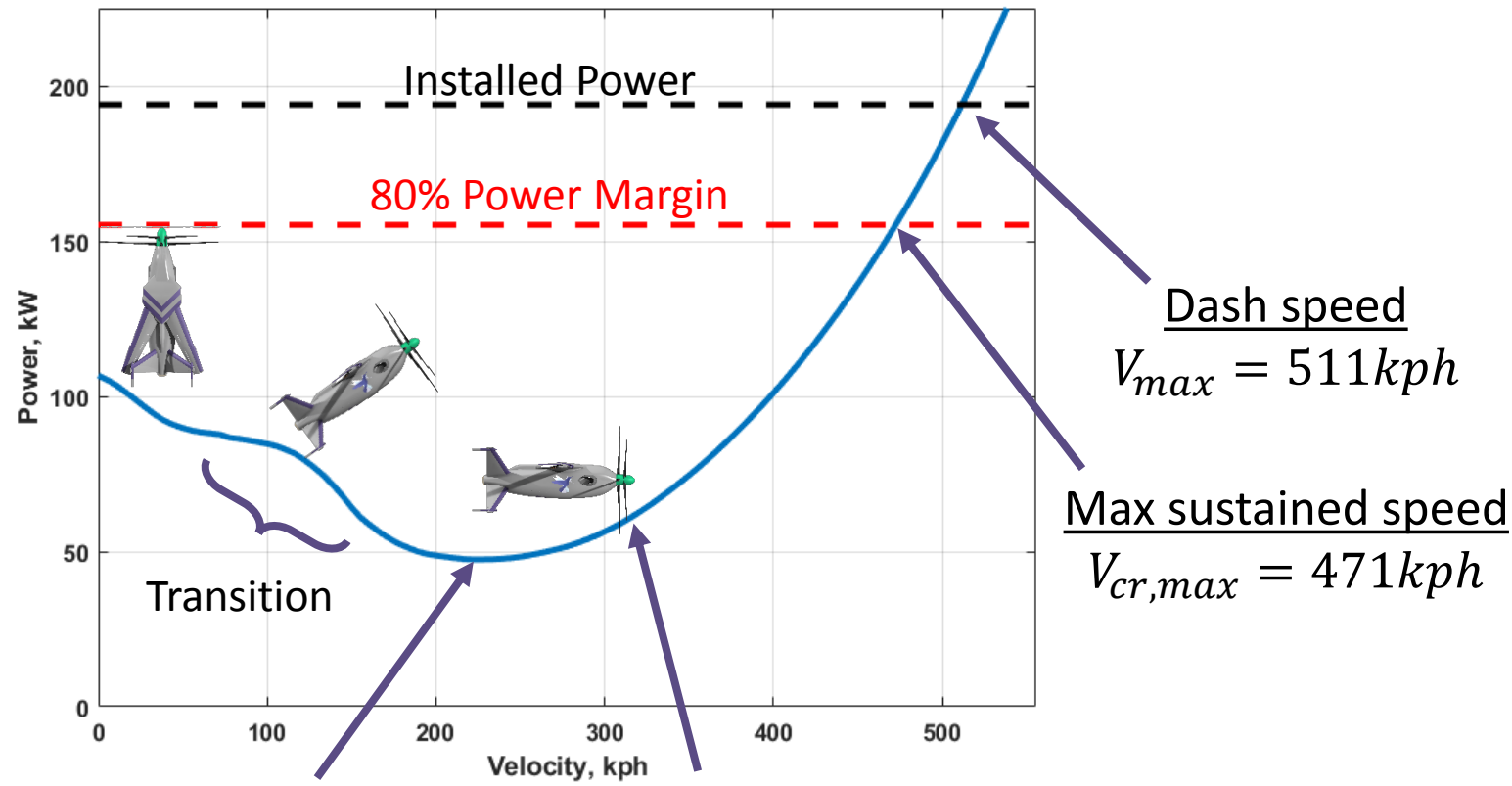


- Clear obstructions quickly
- Very small control inputs



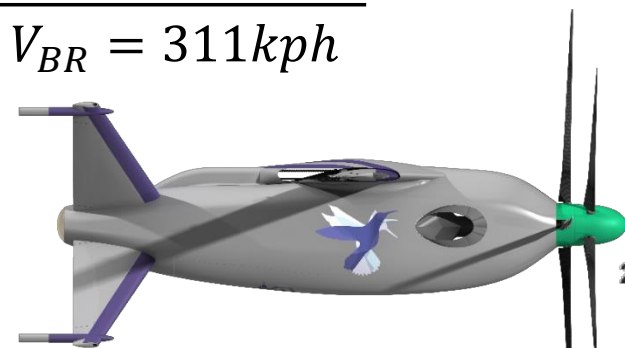


# Vehicle Performance: Faster, Higher, Farther



Best endurance  
 $V_{BE} = 222kph$

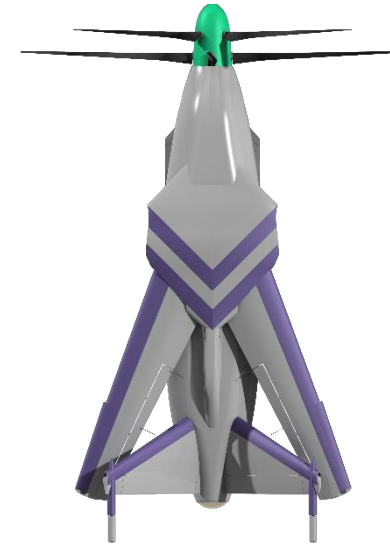
Most efficient cruise  
 $V_{BR} = 311kph$



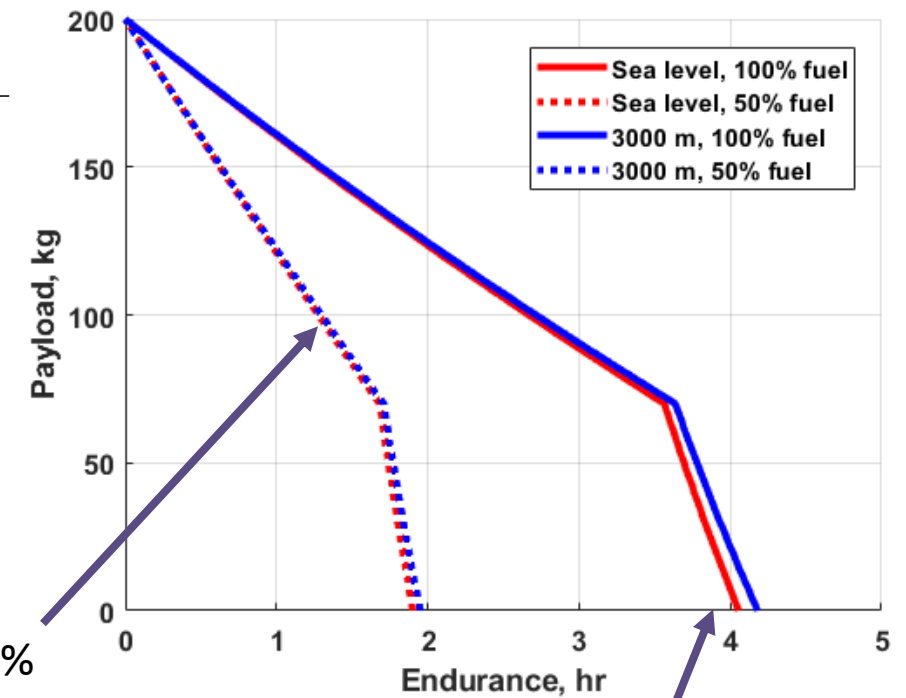
*Metaltail* combines an advanced proprotor with a highly streamlined fuselage:

- As efficient as a **helicopter in hover**
- **Faster** than any current fixed-wing aircraft of similar size
- Up to **12 km/kg** fuel economy for long range and low operational cost

## Efficient in Hover...



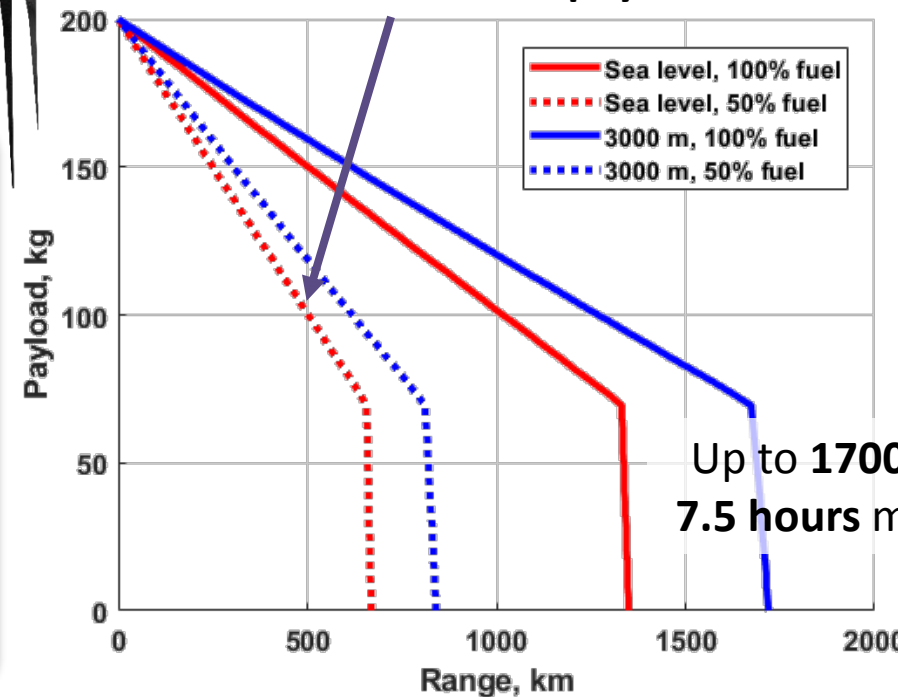
80 minutes hover using 50% fuel with full mission payload



Up to 4 hours hover endurance

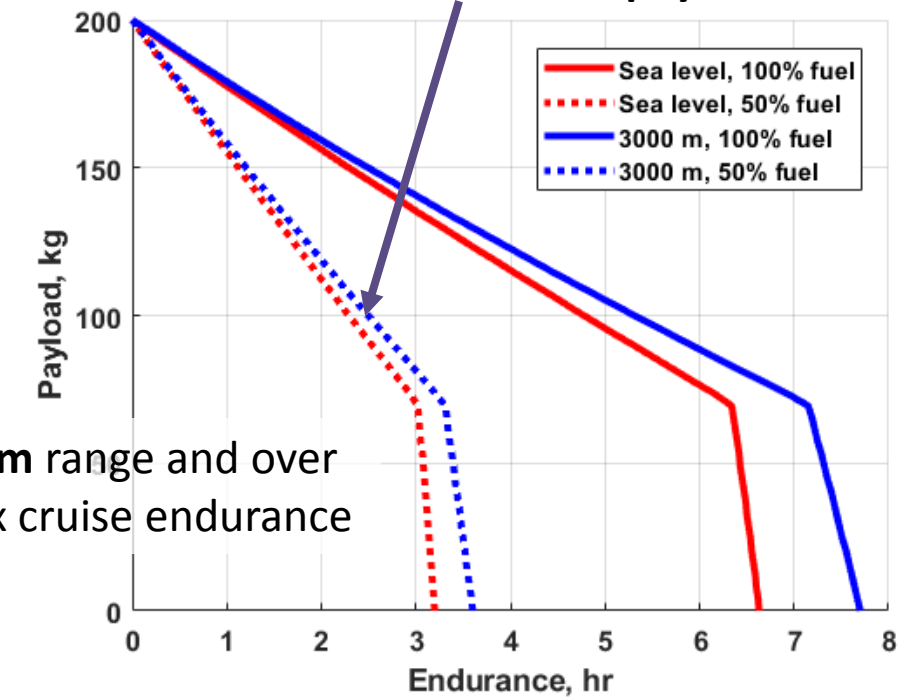
## ...and in Cruise

>500 km range using 50% fuel with full mission payload



Up to 1700 km range and over 7.5 hours max cruise endurance

2.5 hours endurance using 50% fuel with full mission payload



# Avionics: State of the Future

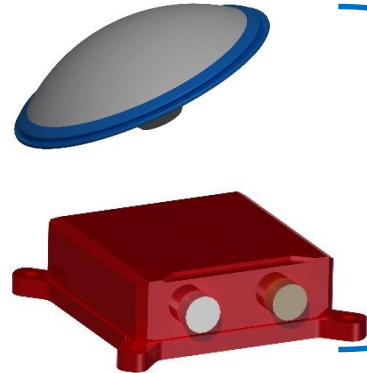


## Event-based camera (x5)

No image blur  
50 million pixel updates per second  
>10x subpixel sampling  
Low light requirements  
Visual dead-reckoning as backup for GPS

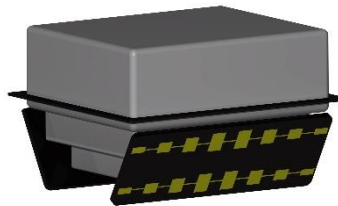
## IMU/GPS

10g  
5cm real-time heave accuracy  
0.01deg roll/pitch accuracy  
<1m global position accuracy  
Low power, low mass antenna



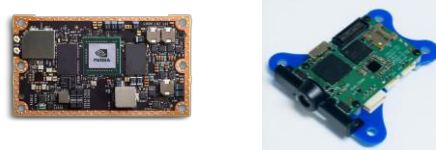
## RADAR

Shoebbox-size  
1kg  
Altimeter and TCAS/GCAS



## Autopilot

Fully autonomous  
<200g  
Powerful main computer:  $10^{13}$  instructions per second  
Reduced backup computer:  $10^9$  instructions per second

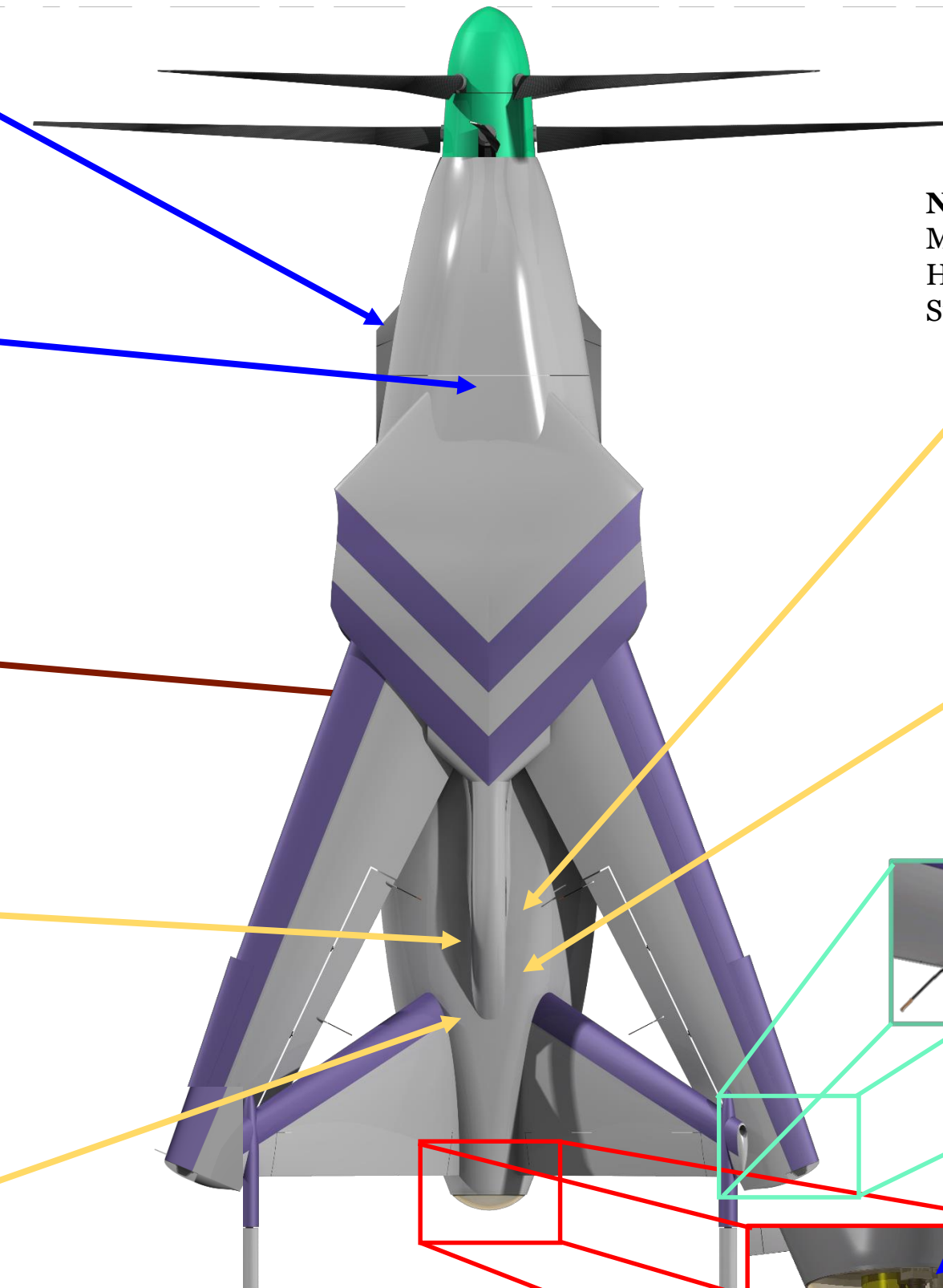


## Data connection anywhere

10 Mbps uplink  
Option for remote pilot  
WiFi in city  
Enterprise satellite network elsewhere

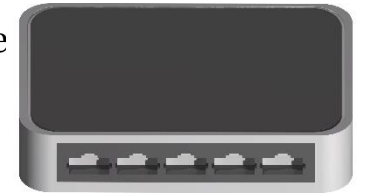


— Top  
— Inside  
— Bottom



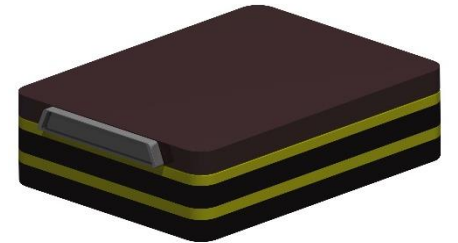
## Networking

Modern point-to-point architecture  
High routing redundancy  
Simple configuration



## Transponder

Low power  
Mode C requirement  
Distance measuring equipment as backup for GPS



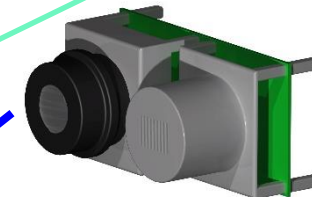
## Pressure/temperature (x2)

Gust data



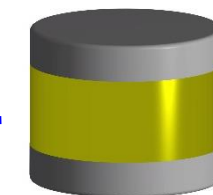
## Downward LIDAR

200m range  
<200g

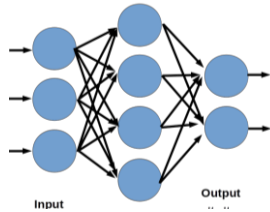


## Scanning LIDAR

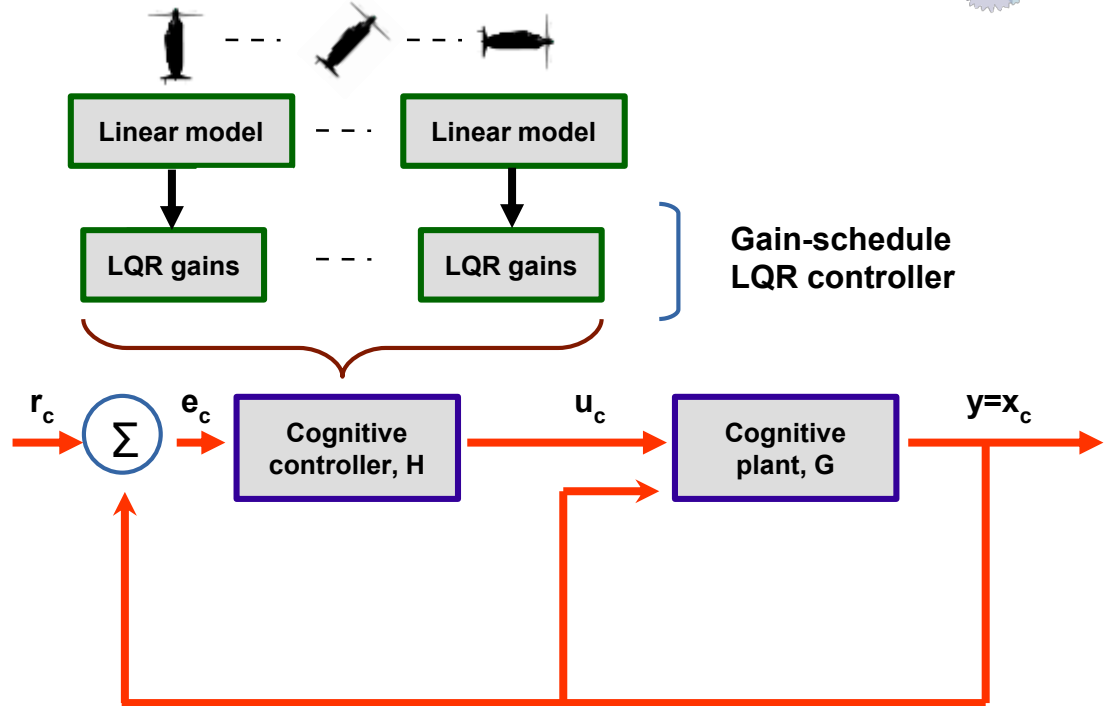
Dust/rain penetrating  
LIDAR filter techniques  
100m range



# Cognitive Controller



G: Predict vehicle response  
H: Determine actuator output



## Analytical:

$$H_i \rightarrow \hat{u} - u_{LQR}$$

$$= e$$

$$H_{i+1} = H_i - \frac{\delta u}{\delta H_i} e$$

State-of-art neuromorphic design

## Flight:

$$G_i \rightarrow \hat{y} - y_{KF,i+1} = r$$

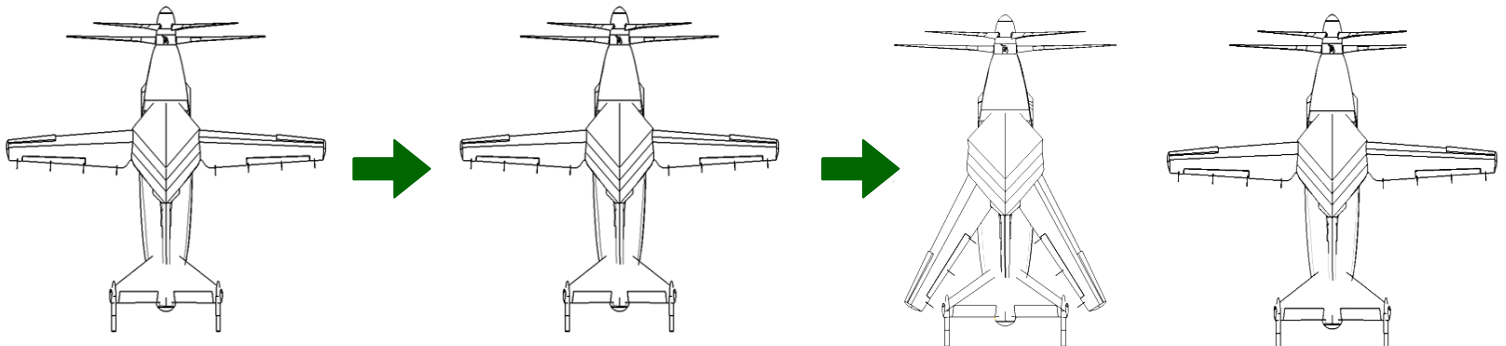
$$H_i \rightarrow \hat{u} - R(r)$$

$$G_{i+1} = G_i + \frac{\delta y}{\delta G_i} r$$

Simple to regress to reliable controller or revert to prior controller state

Tunable, simple to change heuristic for controller characteristics

Proven optimality for a given heuristic

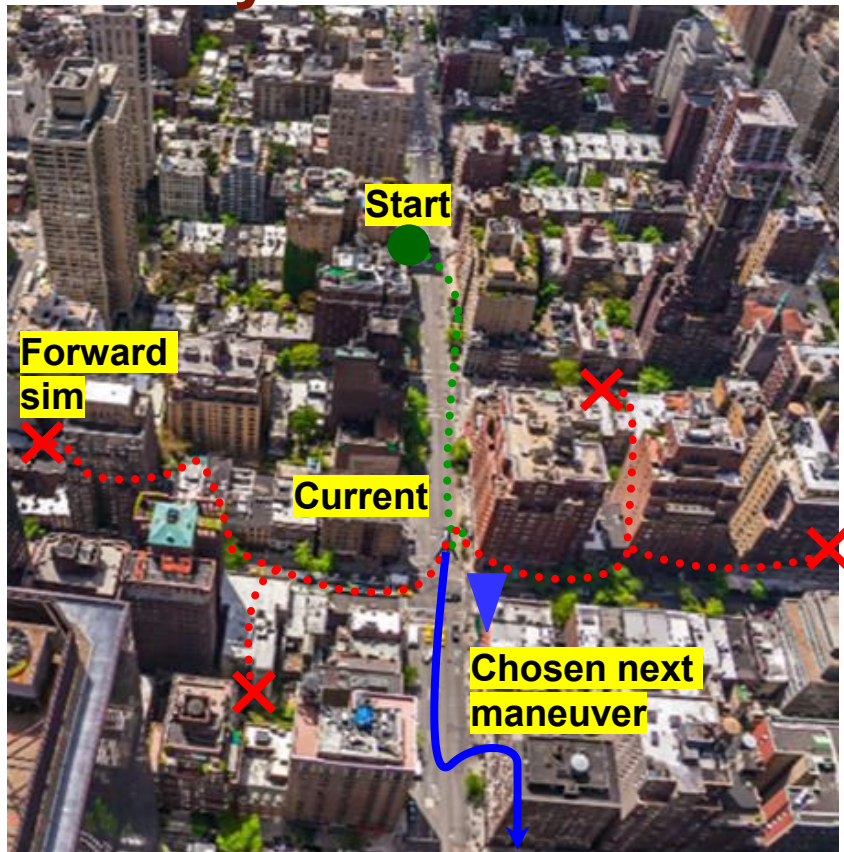


Learn full-vehicle model robust to stochastic effects

# Assured Autonomous Navigation



## Bird's eye view



Cognition in real-world conditions

Instantaneous decision-making

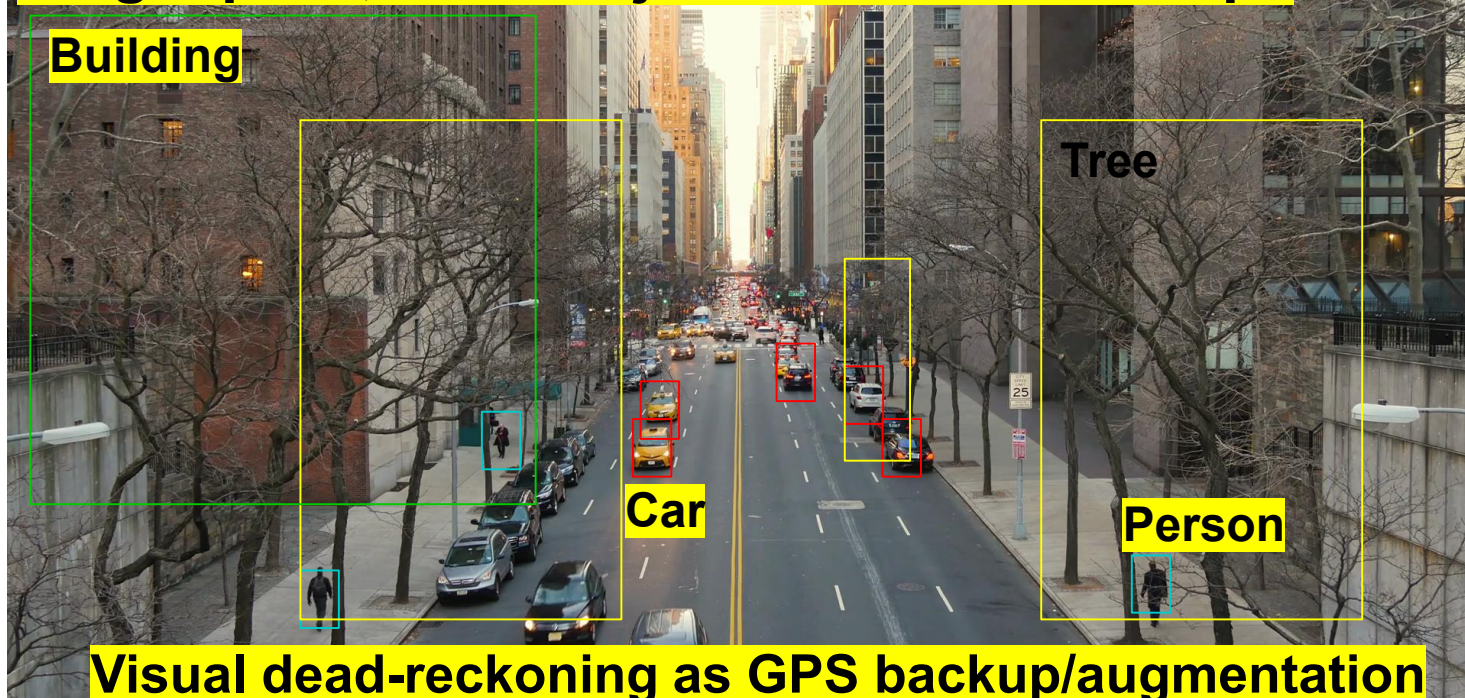
Minimal memory requirement

Context-sensitive to vehicle state, disturbance, and noise

Fast convergence to global optimal path via asynchronous training

## Camera view

Single-pass, multi-object detection at 60 fps

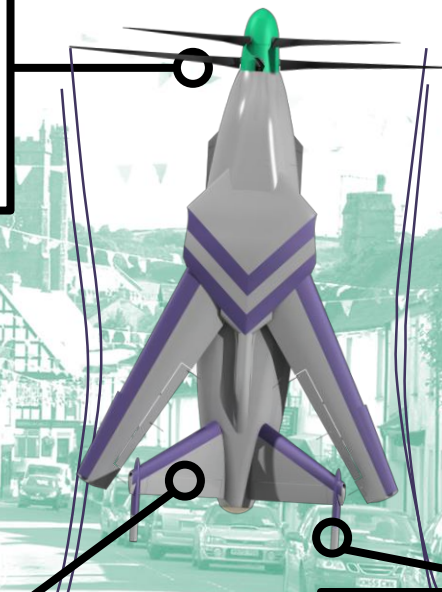


# Safety Driven Design



## Standard Urban Operation

Coaxial rotor reduces downwash velocity compared to single rotor of the same dimension, preventing disturbance of sediment or litter.

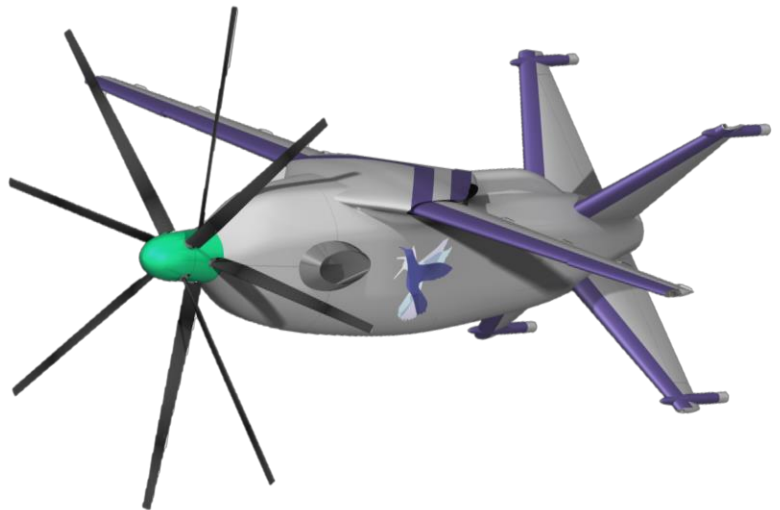


Tailsitter configuration ensures rotors are high and far from ground crew.

Oleo struts sized to FAR 27.725 requirement of 10 ft/s drop velocity.

## In flight failures:

- Metaltail's two 97 kW engines provides One Engine Inoperable (OEI) capability
- Back up power sustains control surface operability to maneuver Metaltail in a glide to a remote area

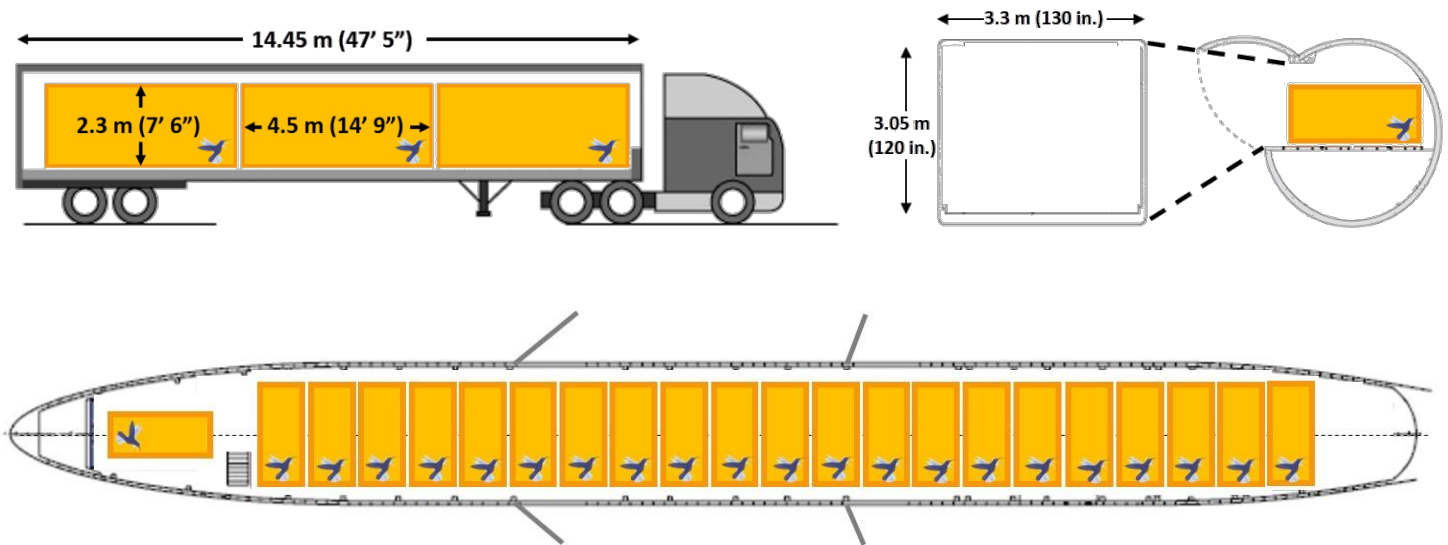


# Concept of Operations



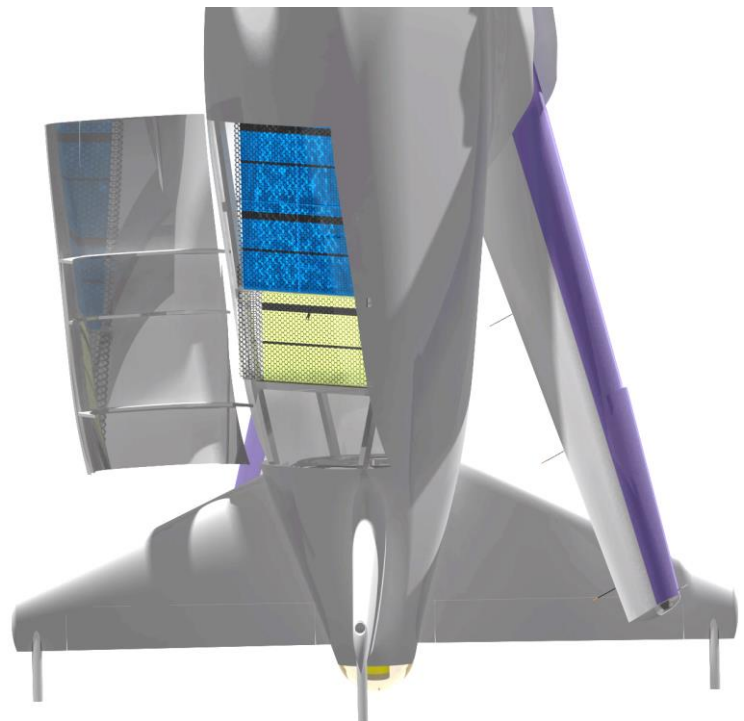
Metaltail comes fully assembled, shipped in a custom shipping crate, 2.3 x 2.3 x 4.5 meters. Three crates fit end to end in a standard 15 meter dry van semi-trailer. Twenty-two crates can fit in a B747-8F main cargo hold for mass emergency deployment to disaster relief sites.

Metaltails are mission ready out of the box.



Metaltail's payload volume is 0.2 cubic meters, double the minimum required volume of the RFP.

Metaltail's payload rack can be removed and replaced with other custom racks with mission-specific equipment.

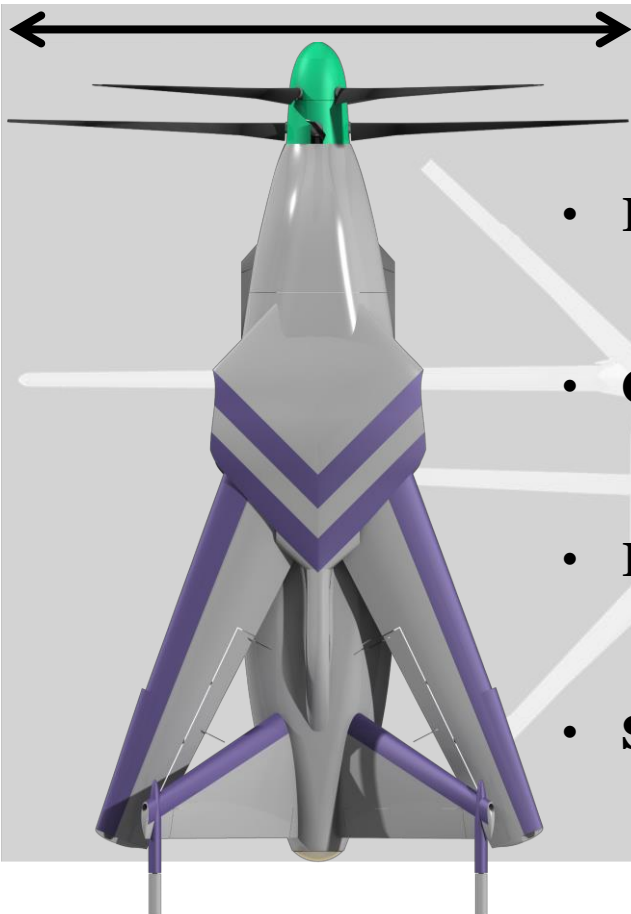


# Metaltail Performance Metrics



Metrics	Conditions	Metaltail Value
<b>Hover Time, hours</b> (using 50% fuel)	SLS	1.28
	3000 m	1.30
<b>Cruise Range, km</b> (at $V_{BR}$ using 50% fuel)	SLS	502
	3000 m	619
<b>Dash Speed, km/h</b> ( $V_{max}$ )	SLS	454
	3000 m	511
<b>Drag Area, m<sup>2</sup></b> (at $V_{max}$ )	SLS	0.1303
	3000 m	0.1306

3 meters



- **Reconfigurable**
  - Novel swing wing design allows efficient hover and forward flight
- **Compact**
  - Fits in a 3 meter by 3 meter square
- **Efficient** in hover and forward-flight
  - Figure of Merit of 0.768
  - Propulsive Efficiency of 0.832
- **Safe**
  - Autonomous assurance
  - Ground clearance